

Phys 5701 22 SEP

From Last Class

$$|\alpha, t_0; t\rangle = U(t, t_0) |\alpha, t_0\rangle \quad t > t_0$$

$$\Leftrightarrow \left[ i\hbar \frac{\partial}{\partial t} U(t, t_0) = H U(t, t_0) \right]$$

$$\underline{\underline{\text{so}}} \quad i\hbar \frac{\partial}{\partial t} |\alpha, t_0; t\rangle = H |\alpha, t; t_0\rangle$$

Project onto representation.

e.g.  $|\pm\rangle$  or  $|\vec{x}'\rangle$

$\Leftrightarrow$  "Normal" Differential Equations.

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But First: For  $H$  independent of time

$$\Leftrightarrow U(t, t_0) = \exp \left[ -\frac{i}{\hbar} H (t - t_0) \right]$$

$\Rightarrow$  Study evolution directly!

$$H |\pm\rangle = E_{\pm} |\pm\rangle \dots$$

Today: Schrödinger Picture  
vs Heisenberg Picture

Consider unitary operator  $U |\alpha\rangle = |\beta\rangle$

$$\langle A \rangle_\beta = \langle \beta | A | \beta \rangle = [\langle \alpha | U^\dagger] A [U | \alpha \rangle]$$

$$= \langle \alpha | [U^\dagger A U] | \alpha \rangle$$

Two "pictures". (1)  $|\alpha\rangle \rightarrow |\beta\rangle$   
(2)  $A \rightarrow U^\dagger A U$

Example:  $J(d\vec{x}) |\alpha\rangle = [1 - \frac{i}{\hbar} \vec{p} \cdot d\vec{x}'] |\alpha\rangle$

$$J^\dagger(d\vec{x}') \vec{x} J(d\vec{x}')$$

$$= [1 + \frac{i}{\hbar} \vec{p} \cdot d\vec{x}'] \vec{x} [1 - \frac{i}{\hbar} \vec{p} \cdot d\vec{x}']$$

$$= \vec{x} + \frac{i}{\hbar} [(\vec{p} \cdot d\vec{x}') \vec{x} - \vec{x} (\vec{p} \cdot d\vec{x}')]$$

But  $(\vec{p} \cdot d\vec{x}') x_i - x_i (\vec{p} \cdot d\vec{x}')$

$$= p_j dx'_j x_i - x_i p_j dx'_j$$

$$= - (x_i p_j - p_j x_i) dx'_j$$

$$= - [x_i, p_j] dx'_j = - i\hbar \delta_{ij} dx'_j = - i\hbar dx'_i$$

$$\Leftrightarrow \int^+ (dx') \vec{x} \int (dx')$$

$$= \vec{x} + \frac{i}{\hbar} (-i\hbar dx')$$

$$= \vec{x} + dx' \mathbf{1}$$

Right!

Apply to  $U(t, t_0)$

$$\text{Take } t_0 = 0 \Rightarrow U(t) = e^{-iHt/\hbar}$$

$$(1) \underline{|\alpha, t\rangle} = U(t) |\alpha\rangle \quad \underline{\langle A \rangle} = \langle \alpha, t | A^{(s)} | \alpha, t \rangle$$

"Schrödinger Picture"

$$(2) \langle A \rangle = \langle \alpha | A^{(H)} | \alpha \rangle$$

$$\underline{A^{(H)} = U^\dagger(t) A^{(s)} U(t)}$$

$$= A^{(H)}(t)$$

"Heisenberg Picture"

$$\frac{d}{dt} A^{(H)}(t) \quad \underline{\text{w/ all}} \text{ time dependence is } U(t)$$

$$= \left[ \frac{\partial U^\dagger(t)}{\partial t} \right] A^{(S)} U(t) + \underbrace{U^\dagger(t) A^{(S)} \frac{\partial U(t)}{\partial t}}$$

$$\text{But } \frac{\partial U}{\partial t} = \frac{1}{i\hbar} H U \Rightarrow \frac{\partial U^\dagger}{\partial t} = -\frac{1}{i\hbar} U^\dagger H$$

$$\begin{aligned} \stackrel{\text{so}}{=} \frac{d}{dt} A^{(H)}(t) &= \frac{1}{i\hbar} \left[ U^\dagger A^{(S)} H U - U^\dagger H A^{(S)} U \right] \\ &= \frac{1}{i\hbar} \left[ U^\dagger A^{(S)} U H - H U^\dagger A^{(S)} U \right] \\ &= \frac{1}{i\hbar} \left[ A^{(H)} H - H A^{(H)} \right] \end{aligned}$$

$$\text{So } \boxed{\frac{d}{dt} A(t) = \frac{1}{i\hbar} [A, H]}$$

in Heisenberg Picture.

note:  $U^\dagger H U = H \underline{U^\dagger U} = H$

"Heisenberg Equation of Motion"

## Application: Free Particles

$$H = \frac{1}{2m} \vec{p}^2 = \frac{1}{2m} [p_x^2 + p_y^2 + p_z^2]$$
$$= \frac{1}{2m} p_i p_i$$

Momentum

$$\frac{dp_i}{dt} = \frac{1}{i\hbar} [p_i, H] = 0$$

$$[x_i, p_j] = i\hbar \delta_{ij}$$

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Position

$$\frac{dx_i}{dt} = \frac{1}{i\hbar} [x_i, H] = \frac{1}{i\hbar} \frac{1}{2m} [x_i, p_j p_j]$$

$$\begin{aligned} [x_i, p_j p_j] &= x_i p_j p_j - p_j p_j x_i \\ &= x_i p_j p_j - p_j x_i p_j + p_j x_i p_j - p_j p_j x_i \\ &= [x_i, p_j] p_j + p_j [x_i, p_j] \\ &= i\hbar \delta_{ij} p_j + p_j i\hbar \delta_{ij} \\ &= 2i\hbar p_j \end{aligned}$$

$$\frac{dx_i}{dt} = \frac{1}{i\hbar} \frac{1}{2m} 2i\hbar p_i = \frac{p_i}{m}$$

i.e.  $\frac{dx_i}{dt} = \frac{\vec{p}}{m}$  or  $\vec{p} = m \frac{dx_i}{dt}$  Right!

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I calculated  $[x_i, \vec{p}^2] = 2i\hbar p_i$

But  $[x_i, F(\vec{p})] = i\hbar \frac{\partial F}{\partial p_i}$  (2.97a)

and  $[p_i, G(x)] = -i\hbar \frac{\partial G}{\partial x_i}$  (2.97b)

Now  $H = \frac{1}{2m} \vec{p}^2 + \underbrace{V(\vec{x})}_{\text{min}} = \frac{1}{2} m \omega^2 x^2$

still  $\frac{d\vec{x}}{dt} = \frac{1}{m} \vec{p}$  because  $[x_i, V(\vec{x})] = 0$

$$\frac{dp_i}{dt} = \frac{1}{i\hbar} [p_i, H] = \frac{1}{i\hbar} [p_i, V(\vec{x})]$$

But  $[p_i, V(\vec{x})] = -i\hbar \frac{\partial V}{\partial x_i}$

i.e.  $[\vec{p}, V(\vec{x})] = -i\hbar \vec{\nabla} V$

i.e.  $\frac{d\vec{p}}{dt} = \frac{1}{i\hbar} (-i\hbar \vec{\nabla} V) = -\vec{\nabla} V = \vec{F}$

Newton's 2<sup>nd</sup> law

OR  $\frac{d}{dt} \langle \vec{p} \rangle = - \langle \vec{\nabla} V \rangle$

"Ehrenfest Theorem"