

Phys 3701 Inho QM I 2 Feb 2021

Class online today due to Snowstorm

Today: Angular Momentum & Commutation

Reminder: Rotation operator for a state

$$\hat{R}(\phi \hat{k}) = e^{-i \hat{J}_z \phi / \hbar} \quad (\text{about } z\text{-axis})$$

$$\hat{R}(d\phi \hat{k}) = \hat{1} - \frac{i}{\hbar} \hat{J}_z d\phi \quad \text{Infinitesimal } d\phi$$

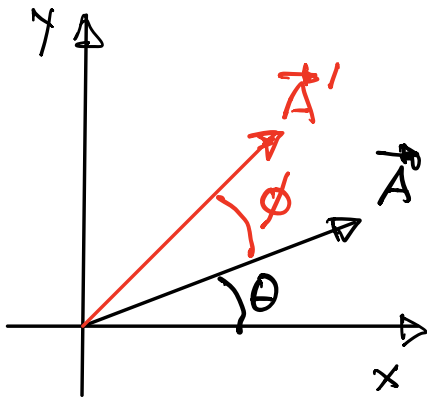
Same thing for rotations about  
x-axis or y-axis:

$$\hat{R}(d\phi \hat{i}) = \hat{1} - \frac{i}{\hbar} \hat{J}_x d\phi + \mathcal{O}(d\phi^2)$$

$$\hat{R}(d\phi \hat{j}) = \hat{1} - \frac{i}{\hbar} \hat{J}_y d\phi + \mathcal{O}(d\phi^2)$$

$\hat{J}_x, \hat{J}_y, \hat{J}_z$  = "generators of rotation"  
aka "angular momentum"

"Rotations Do Not Commute!"



$$\checkmark A_x = A \cos \theta \quad \checkmark A_y = A \sin \theta$$

$$A'_x = A \cos(\theta + \phi) \quad \checkmark$$

$$A'_y = A \sin(\theta + \phi) \quad \checkmark$$

$$A'_x = A \cos \theta \cos \phi - A \sin \theta \sin \phi$$

$$= A_x \cos \phi - A_y \sin \phi$$

$$A'_y = A \sin \theta \cos \phi + A \cos \theta \sin \phi$$

$$= A_x \sin \phi + A_y \cos \phi$$

$$A'_z = A_z$$

$$\begin{bmatrix} A'_x \\ A'_y \\ A'_z \end{bmatrix} = \begin{bmatrix} \cos \phi & -\sin \phi & 0 \\ \sin \phi & \cos \phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix} \quad \mathcal{S}(\phi \hat{k})$$

Also

$$\mathcal{S}(\phi \hat{i}) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \phi & -\sin \phi \\ 0 & \sin \phi & \cos \phi \end{bmatrix}$$



$$\mathcal{S}(\phi \hat{j}) =$$

$$\begin{bmatrix} \cos \phi & 0 & \sin \phi \\ 0 & 1 & 0 \\ -\sin \phi & 0 & \cos \phi \end{bmatrix}$$

$$S(\hat{\phi}_i) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 - \frac{1}{2}d\phi^2 & -d\phi \\ 0 & d\phi & 1 - \frac{1}{2}d\phi^2 \end{bmatrix} \quad S(\hat{\phi}_j) = \begin{bmatrix} 1 - \frac{1}{2}d\phi^2 & 0 & d\phi \\ 0 & 1 & 0 \\ -d\phi & 0 & 1 - \frac{1}{2}d\phi^2 \end{bmatrix}$$

$$S(\hat{\phi}_i)S(\hat{\phi}_j) = \begin{bmatrix} 1 - \frac{1}{2}d\phi^2 & 0 & d\phi \\ d\phi^2 & 1 - \frac{1}{2}d\phi^2 & -d\phi + \mathcal{O}(d\phi^3) \\ -d\phi & d\phi & 1 - d\phi^2 + \mathcal{O}(d\phi^4) \end{bmatrix}$$

$$S(\hat{\phi}_j)S(\hat{\phi}_i) = \begin{bmatrix} 1 - \frac{1}{2}d\phi^2 & d\phi^2 & d\phi \\ 0 & 1 - \frac{1}{2}d\phi^2 & -d\phi \\ -d\phi & d\phi & 1 - d\phi^2 \end{bmatrix}$$

$$S(\hat{\phi}_i)S(\hat{\phi}_j) - S(\hat{\phi}_j)S(\hat{\phi}_i)$$

$$= \begin{bmatrix} 0 & -d\phi^2 & 0 \\ d\phi^2 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{Det } S(d\phi^2 \hat{k}) = \begin{bmatrix} 1 & -d\phi^2 \\ d\phi^2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\boxed{\begin{aligned} S(\hat{\phi}_i)S(\hat{\phi}_j) - S(\hat{\phi}_j)S(\hat{\phi}_i) \\ = \underline{S(d\phi^2 \hat{k})} - 1 \end{aligned}}$$

$$\hat{R}(d\phi^i) = \hat{1} - \frac{i}{\hbar} \hat{J}_x d\phi$$

$$\hat{R}(d\phi^j) = \hat{1} - \frac{i}{\hbar} \hat{J}_y d\phi$$

$$\hat{R}(d\phi^i) \hat{R}(d\phi^j) = \hat{1} - \frac{i}{\hbar} \hat{J}_x d\phi - \frac{i}{\hbar} \hat{J}_y d\phi + \left(\frac{i}{\hbar}\right)^2 \hat{J}_x \hat{J}_y d\phi^2$$

$$\hat{R}(d\phi^j) \hat{R}(d\phi^i) = \hat{1} - \frac{i}{\hbar} \hat{J}_y d\phi - \frac{i}{\hbar} \hat{J}_x d\phi + \left(\frac{i}{\hbar}\right)^2 \hat{J}_y \hat{J}_x d\phi^2$$

$$\hat{R}(d\phi^i) \hat{R}(d\phi^j) - \hat{R}(d\phi^j) \hat{R}(d\phi^i)$$

$$= \left(\frac{i}{\hbar}\right)^2 (\hat{J}_x \hat{J}_y - \hat{J}_y \hat{J}_x) d\phi^2$$

$$= \hat{R}(d\phi^2 \hat{L}) - \hat{1}$$

$$= \hat{1} - \frac{i}{\hbar} \hat{J}_z d\phi^2 - \hat{1}$$

$$\left(\frac{i}{\hbar}\right)^2 (\hat{J}_x \hat{J}_y - \hat{J}_y \hat{J}_x) = -\frac{i}{\hbar} \hat{J}_z = +\frac{i^3}{\hbar} \hat{J}_z$$

$$\hat{J}_x \hat{J}_y - \hat{J}_y \hat{J}_x = i\hbar \hat{J}_z$$

Remindology:  $[\hat{A}, \hat{B}] = \hat{A}\hat{B} - \hat{B}\hat{A} = -[\hat{B}, \hat{A}]$

## "Angular Momentum Commutation Relations"

$$[\hat{J}_x, \hat{J}_y] = i\hbar \hat{J}_z$$

$$[\hat{J}_z, \hat{J}_x] = i\hbar \hat{J}_y$$

$$[\hat{J}_y, \hat{J}_z] = i\hbar \hat{J}_x$$

"cyclic permutation"

$$\hat{J}^2 \equiv \hat{J}_x^2 + \hat{J}_y^2 + \hat{J}_z^2$$

## Commutation and Observables

$$\hat{A} |a\rangle = a |a\rangle$$

$\hat{A}^\dagger = \hat{A}$       Eigenvalue

e.g.  $\hat{J}_z | \pm \frac{1}{2} \rangle = \pm \frac{\hbar}{2} | \pm \frac{1}{2} \rangle$

e.g.  $S_z$  must can only give  $+\frac{\hbar}{2}, -\frac{\hbar}{2}$

Suppose  $[\hat{A}, \hat{B}] = 0 \Rightarrow \hat{A}\hat{B} = \hat{B}\hat{A}$

$$\hat{A} |a\rangle = a |a\rangle \Rightarrow \hat{B}\hat{A} |a\rangle = a \hat{B} |a\rangle$$

$$= \hat{A}\hat{B} |a\rangle \quad \text{"Compatible"}$$

i.e.  $\hat{A} (\hat{B} |a\rangle) = a (\hat{B} |a\rangle)$  i.e.  $\hat{B} |a\rangle = b |a\rangle$