

* Via Zoom from APS 2024

* Homework Posted

* New Syllabus starts today

Quick Review: Wave Mechanics in 1D

Position operator x w/ $x|x\rangle = x|x\rangle$ "operator \rightarrow eigenvalue"

Translation operator $T(a)|x\rangle = |x+a\rangle$

Normalization $\langle x'|x\rangle = \delta(x-x')$

$$\Leftrightarrow 1 = \int dx |x\rangle \langle x|$$

$T(dx) = 1 - \frac{i}{\hbar} dx p$ "Weil's Trick" $\Rightarrow T(a) = e^{-ipa/\hbar}$
 $p =$ "momentum" why?? Well we found that

$$H = \frac{1}{2m} p^2 + V(x) \Rightarrow \frac{d}{dt} \langle x \rangle = \frac{\langle p \rangle}{m} \text{ and } \frac{d\langle p \rangle}{dt} = \left\langle -\frac{dV}{dx} \right\rangle \underline{\underline{OK}}$$

Define $\psi_\alpha(x) \equiv \langle x|\alpha\rangle \Rightarrow \langle x|p|\alpha\rangle = \frac{\hbar}{i} \frac{\partial \psi_\alpha}{\partial x}$

$$\Leftrightarrow H|E\rangle = E|E\rangle \text{ becomes } -\frac{\hbar^2}{2m} \frac{\partial^2 \psi}{\partial x^2} + V(x)\psi(x) = E\psi(x)$$

"Schrödinger Equation"

Also • For "Bound states" have $\psi(x \rightarrow \pm\infty) = 0$

\Leftrightarrow Discrete Energies! (e.g. Box, SHO)

• $\langle x|p|p\rangle = p\langle x|p\rangle$
and $= \frac{\hbar}{i} \frac{\partial}{\partial x} \langle x|p\rangle \Rightarrow \langle x|p\rangle = \frac{1}{\sqrt{2\pi\hbar}} e^{ixp/\hbar}$

Today: Beginn Wave Mechanics in 3D

Position and Momentum in 3D

Position Eigenstate $|\vec{r}\rangle = |x, y, z\rangle$

operator $\vec{r} = x\hat{x} + y\hat{y} + z\hat{z}$ $\hat{x}, \hat{y}, \hat{z}$ unit vectors

i.e. $x|\vec{r}\rangle = x|\vec{r}\rangle$ $y|\vec{r}\rangle = y|\vec{r}\rangle$ $z|\vec{r}\rangle = z|\vec{r}\rangle$
 operator eigenvalue

Tacit assumption: x, y, z are commuting operators!
 Don't assume that \rightarrow "super symmetry" (!)

Normalization

$$\langle \vec{r} | \vec{r}' \rangle = \delta(x-x') \delta(y-y') \delta(z-z') \\ \equiv \delta^{(3)}(\vec{r} - \vec{r}')$$

Wave Function $\psi_{\alpha}(\vec{r}) \equiv \langle \vec{r} | \alpha \rangle$

$$\Leftrightarrow 1 = \langle \alpha | \alpha \rangle = \int d^3r \langle \alpha | \vec{r} \rangle \langle \vec{r} | \alpha \rangle = \int d^3r \psi_{\alpha}^*(\vec{r}) \psi_{\alpha}(\vec{r})$$

Translation Operator: Now it has a vector argument

$$T(a_x \hat{x}) |x, y, z\rangle = |x+a_x, y, z\rangle$$

$$T(a_y \hat{y}) |x, y, z\rangle = |x, y+a_y, z\rangle$$

$$T(a_z \hat{z}) |x, y, z\rangle = |x, y, z+a_z\rangle$$

$$\text{i.e. } T(\vec{a}) |\vec{r}\rangle = |\vec{r} + \vec{a}\rangle$$

We already have

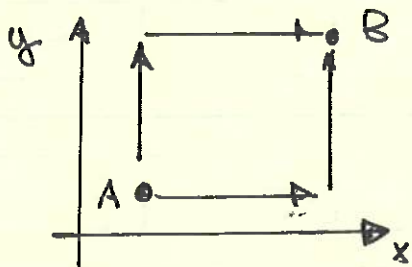
$$T(a_x \hat{x}) = e^{-ip_x a_x / \hbar}$$

$$T(a_y \hat{y}) = e^{-ip_y a_y / \hbar}$$

$$T(a_z \hat{z}) = e^{-ip_z a_z / \hbar}$$

} Same argument as for "x"
i.e. $dx = \lim_{N \rightarrow \infty} \frac{a_x}{N}$ etc...

Important: Translations commute



$$\text{i.e. } T(a_y \hat{y}) T(a_x \hat{x}) = T(a_x \hat{x}) T(a_y \hat{y})$$

\Leftarrow Put $a_x = dx$, $a_y = dy$ and go to second order to find $[p_x, p_y] = 0$ Homework!

"Momentum components commute" $\Rightarrow |p_x, p_y, p_z\rangle = |\vec{p}\rangle$ ok!

This also means that we can write...

$$T(a_x \hat{x}) T(a_y \hat{y}) T(a_z \hat{z}) = e^{-i(p_x a_x + p_y a_y + p_z a_z) / \hbar} = e^{-i\vec{p} \cdot \vec{a} / \hbar}$$

... because the p_x, p_y, p_z all commute!

Back to 1D for a moment

We showed $(x T(\delta x) - T(\delta x) x) = -\frac{i}{\hbar} \delta x [x, p_x]$

and $(x T(\delta x) - T(\delta x) x) |\alpha\rangle = \delta x |\alpha\rangle \Leftarrow x T(\delta x) \rightarrow (x + \delta x)$

\Leftarrow $[x, p_x] = i\hbar$ "Canonical commutation Relation"

So it follows directly that

$$[y, p_y] = i\hbar \quad \text{and} \quad [z, p_z] = i\hbar$$

But what about other combinations?

i.e. Do y and $T(a_x \hat{x})$ commute?

$$\begin{aligned} T(a_x \hat{x}) y |\alpha\rangle &= T(a_x \hat{x}) y \int d^3r |x, y, z\rangle \langle x, y, z | \alpha \rangle \\ &= T(a_x \hat{x}) \int d^3r \overset{\text{oper.}}{y} |x, y, z\rangle \langle x, y, z | \alpha \rangle \quad \leftarrow \text{eigenvalue} \\ &= \int d^3r y T(a_x \hat{x}) |x, y, z\rangle \langle x, y, z | \alpha \rangle = y T(a_x \hat{x}) |\alpha\rangle \end{aligned}$$

i.e. $y T(a_x \hat{x})$ has no eigenvalue change!

then take it out!

yes $\Rightarrow [y, p_x] = 0$ etc...

i.e. $\underline{\underline{[r_i, p_j] = i\hbar \delta_{ij}}}$ $r_1, r_2, r_3 = x, y, z$
 $p_1, p_2, p_3 = p_x, p_y, p_z$

Momentum Eigenstates $|p_x, p_y, p_z\rangle = |\vec{p}\rangle$

$$\langle \vec{p} | \vec{p}' \rangle = \delta^{(3)}(\vec{p} - \vec{p}')$$

and as before $\langle \vec{r} | \vec{p} \rangle = \frac{1}{i} \left(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \right) \underline{\underline{\langle \vec{r} | \alpha \rangle}}$

$$= \frac{1}{i} \underline{\underline{\nabla}} \underline{\underline{\psi_\alpha(\vec{r})}}$$

and $\langle \vec{r} | \vec{p} \rangle = \frac{1}{(2\pi\hbar)^{3/2}} e^{i\vec{p} \cdot \vec{r} / \hbar}$

Translational Invariance

aka "Translational Symmetry"

Consider a two-particle Hamiltonian:

$$H = \frac{1}{2m_1} \vec{p}_1^2 + \frac{1}{2m_2} \vec{p}_2^2 + \underline{V(|\vec{r}_1 - \vec{r}_2|)}$$

Only depends on difference!

↳ Expect translational invariance!

Formal: $T_{12}^\dagger H T_{12} = H$ (See Homework)

$$\text{w/ } T_{12} = T_1(\vec{a}) T_2(\vec{a}) = e^{-i \vec{P} \cdot \vec{a} / \hbar}$$

where $\vec{P} = \vec{p}_1 + \vec{p}_2$ "total momentum"

Find $[\vec{P}, H] = 0$

But $\frac{d}{dt} \langle \vec{P} \rangle = \frac{i}{\hbar} \langle [H, \vec{P}] \rangle = 0$

Recall: $d\langle A \rangle / dt$
 $= d/dt \langle \alpha, t | A | \alpha, t \rangle$

etc...

↳ "Total momentum is conserved"

We saw the same result in
 Analytical Mechanics!

"Conservation Laws are Fundamental"

↳ Much of this physics follows directly
 from classical mechanics

e.g. Relative and CM coordinates

Better operators for two-body systems

$$\vec{r} \equiv \vec{r}_1 - \vec{r}_2 \quad \text{"relative"}$$

$$\vec{R} \equiv (m_1 \vec{r}_1 + m_2 \vec{r}_2) / (m_1 + m_2) \quad \text{"CM"}$$

Might not have
time for this,
but that's ok.

NOTE $[\vec{r}_i, \vec{p}_j] = 0$

e.g. $[x_1 - x_2, p_1 + p_2] = [x_1, p_1] - [x_2, p_2] = 0$

Expected from Translational Invariance!

ALSO $[\vec{R}_i, \vec{p}_j] = i\hbar \delta_{ij}$ (Work it out)

\Leftrightarrow Define relative momentum $\vec{p} = \frac{m_2 \vec{p}_1 - m_1 \vec{p}_2}{m_1 + m_2}$

$\Leftrightarrow [\vec{r}_i, \vec{p}_j] = i\hbar \delta_{ij}$ (Work it out)

\Leftrightarrow we can treat two-body systems just using the relative coordinate and reduced mass.

(As Expected).

But mention this...

Upshot: we will now consider Hamiltonians

$$H = \frac{1}{2m} \vec{p}^2 + V(|\vec{r}|) \quad \text{"Relative } \vec{r} \text{ and } \vec{p} \text{ in Two-Body System"}$$

$$m = \frac{m_1 m_2}{m_1 + m_2} \quad \text{"Reduced Mass"}$$

"Central Potential"

i.e. Spherically Symmetric