ØDE	Approximate	on			• •	
· · ·	x'(+) = x(t_) =	f(x) Xo india	rt condition	Z initial	value	proton
Cov	nsider Yh	e autonou	nens case,	Here to	= D .	
Want	10 N	Umeri'cally	approximate	solution a	7 ODE	
	×↑	· · · · ·			• •	
		$x \approx x(t_{1})$	approxim	este schutron	а. с. с. <u>ј</u> е	
					R XH	E)
		· · · · ·				
• • •	X _o	error		· · · · ·	• •	True solution
· · ·		. emer t t t	· · · · ·	+ $+$ $+$ $+$ $+$ $+$ $+$ $+$ $+$ $+$		True solution
· · · ·	Xo O At	. emer		I I tf final	tine	
Consider	Vo O At n steps	error	t 	= tf	tihne tine	
Consicler	Vo O At n steps	$t_{j} = j$	t 	$i = t_{f}$ $j = 1, \dots, n$	tihre	
Consider	Vo O At n steps	$t_{j} = j$	t 	$j = 1, \dots, n$	tine	J rue Solution . . .

Solutra curve	r to I function	clifferent that c	ral eq lepends	on t	is an	i unki	rwn	•
Differe tange	rtral equa nt line	ution giv at an	es for 1 point	mula f t on	r (om the	puting unknew	slope c on cur	τ f ve
We Hhe Succe	are given solution ssive poin	the i curve ts or f	initial & the he cur	cand inv task ve.	n — ís to	one f fnd	00 nt	ØV
Consic	ler the	slope i	of the	tangei	ot lin	e oct	• •	•
X _o	H is	given by	· · ·	$P(x_{o})$.	• •		• •	•
Euler	Method	for appro	xinulng	ODES	says	we.	Can	•
find	an appro	ximute V	alue a	rf X	at	$t_1 = \Delta t$	E	•
<u>i</u> el	X _I ∝ xl	tı) by	a ssum	ing	×, –	X ₀ =	f(xo)	•
So	. χ _ι .Ξ.	X0 + 6t.	f(xo)	• •	• •	• • •	• •	•
To find then	X ₂ w	e assume	× × ×	really	is equ	ral to	x (+,)	•
	X ₂ =	x' + γ	ťť(X,)	• •	• •	• • •	• •	•
• • •			• • •	• •	• •	• • •	• •	•

Euler of H	Method ne po	d (unts	loes	Huis	a	ppro	xim	.wtro	n	for	the	, rel	5+	•	· •
Cien	eral	form	ula	• •	For	war	e l	ule	r	•	•		•	•	•
	X _j	. = .	X;-1	; ; + ;	۵t	•	f()	(j-1)	• •	•	· j	= , ·	, n	•	•
	• •	• •	٠	• •	٠	•	•	•	• •	٠	•	• •	•	• •	
	Xj	/ ~	x l	(tj)	=	хl	j∆ł)	• •	•	•	• •	•	• •) e
	• •	• •	•	•••	•	•	•	•	• •			• •	•	•	, . 7
What	is the	2 e	rror	ma	de	in	O	re	step	o	Eul	er 1	vetl	lock	
Su	ppose	χ(t _{j-} ,) =)	(j_1)	•		•	•	• •	•	• •		•	•	• •
approx	X j	1) .	×j−ι	+ Δ	t :	f.()	(j.)	•	•	•	•	•	•	• •	• •
true	x(tj)	=	x (tj	-, + L	st)	•	•	•	• •	•	•	•	•	• •	• •
		 =	x/t:	 .) +		.#γ	'(+:_) +	<u> </u>	(At) ² x"		.+	0(St3)
• • • •	• •	• •		·i. / :		.~				رب		. 5-1)	•		
ej = X (tj)	x; .	 	<u>א</u> (∆ו	;) ² x	("(t	;-i)	†	0(6t ³)	•		•	• •	• •
error at	sep j	• •	٠	• •	•	•	•	•	high	er	order	ten	ms	• •	• •
		• •	•		•	•	•	•	be ca	ve	insi	gnifi	cant	- llor	• •
	• •	• •			٠	•	•	•	ols .	٥t	beco	mes	2 m	und	•
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	• •	• •	•	• •	٠	•	٠	•		٠	•	•	•	•	•

There are $n = \frac{t_{f}}{\Delta t}$ steps => $O(\frac{1}{\Delta t})$ steps
Per step accumulate error $O(\delta t^2)$
Global error $\rightarrow O(\overline{st})O(\overline{st^2}) = O(\overline{st})$
Euler Method is a first order method
Reduce time step size At by 2, error goes down
a factor of 2.
We can do better for example
10 RK2 - Runge-Kutta 2 is a second order scheme
$()(\Delta t^{2})$
$U(\Delta t^2)$ $E \sim O(\Delta t^2) \Rightarrow halve \Delta t \Rightarrow error goes$ down by fictor of 4
$E \sim O(\Delta t^{2}) \implies halve \Delta t \implies error goes$ $E_{\Delta t} = O(\Delta t^{2}) \qquad down \qquad by factor of 4$ $E_{\Delta t} = O((\Delta t^{2})^{2}) = O((\Delta t^{2})^{2})$
$E \sim O(\Delta t^{2}) \implies halve \Delta t \implies error goes$ $E_{\Delta t} = O(\Delta t^{2}) \qquad down \qquad by factor of 4$ $E_{\Delta t} = O((\Delta t^{2})^{2}) = O((\Delta t^{2})^{2})$
$E \sim O(\Delta t^{2}) \implies halve \Delta t \implies envor goes$ $E_{\Delta t} = O(\Delta t^{2}) \qquad down by factor of 4$ $E_{\Delta t} = O((\Delta t^{2})^{2}) = O((\Delta t^{2})^{2})$ $E_{\Delta t} = O(((\Delta t^{2})^{2})) = O((\Delta t^{2})^{2})$ $R_{A} is a fourth order scheme O(\Delta t^{4})$ $halve \Delta t \implies envor goes down by factor of 16!$
$E \sim O(\Delta t^{2}) \implies halve \Delta t \implies error goes$ $E_{\Delta t} = O(\Delta t^{2}) \qquad down \qquad by factor of 4$ $E_{\Delta t} = O((\frac{\Delta t^{2}}{2})) = O(\frac{\Delta t^{2}}{4})$ $E_{\Delta t} = O((\frac{\Delta t}{2})) = O(\frac{\Delta t^{2}}{4})$ $error goes down \qquad by factor of 16.$ Better accuracy
$E \sim O(\Delta t^{2}) \implies halve \Delta t \implies error goes$ $E_{\Delta t} = O(\Delta t^{2}) \qquad olown by factor of 4$ $E_{\Delta t} = O((\Delta t^{2})^{2}) = O((\Delta t^{2})^{2})$ $E_{\Delta t} = O(((\Delta t^{2})^{2})) = O((\Delta t^{2})^{2})$ $RK4 is a fourth order scheme O(\Delta t^{4})$ $halve \Delta t \implies error goes dann by factor of 16!$ $Better accuracy$
$E \sim O(\Delta t^{2}) \implies halve \Delta t \implies error goes$ $E_{\Delta t} \equiv O(\Delta t^{2}) \qquad down \qquad by factor of 4$ $E_{\Delta t} \equiv O((\Delta t^{2})^{2}) \equiv O((\Delta t^{2})^{2}) \equiv O((\Delta t^{2})^{2})$ $E_{\Delta t} \equiv O(((\Delta t^{2})^{2})) \equiv O((\Delta t^{2})^{2})$ $RK4 \qquad is a fourth order schene O(\Delta t^{4})$ $halve \Delta t \implies error goes down \qquad by factor of 16^{1}.$ $Better accuracy$

COVID-19 Modeling	• •	· · · · · ·
Model how disease spreads	• •	
10 Agent Based Approach	• •	· · · · · ·
think contagion code Represent humans as agents and simulate	what	herppens
when they interact and possibly pass	disease	on
The ABM can include characteristics of de 1. ppsbability of mection	isease	
2. likelihood of them staying infected 3. amount of the needed to recover	d er	· · · · · ·
ABM can also build in agent attributes population demographics like	to	match
age, profession, student/nonstudent, someone lives etc.	where	· · · · · ·
	• •	
Build a simulation then try add in to see effects	policy	interventions
i) Mask wearny ii) Social distuncting iii) Quarantine / Isdahan		
iv) Vaccination (hard)	- • •	

2.	Differential Equation Models	• •
• •	Don't resolve the population to its finer details instead group into broad classes <u>eg</u> .	· ·
	SIR model Simple case S(t) number of susceptible individuals	• •
• •	I lt) number of infected individuals R (t) number of recovered individuals	
• •	Suppose we have a total population N we can	• •
• •	$s(t) = \frac{S(t)}{N}$	••••
• •	$i(t) = \frac{I(t)}{N}$	• •
• •	N	• •
T	The differential modeling idea is to figure out how s(t), i'(t), r(t) vary in time.	• •
	Johe that $s(t) + i(t) + r(t) = 1$	• •
•••	$\frac{ds}{dt} = -bs(t)i(t)$	••••
• •	$\frac{dr}{dt} = kilt$	
· ·	$\frac{dt}{dt} = bs(t)i(t) - ki(t)$	• •
	K - constant, probability of recovery	• •

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